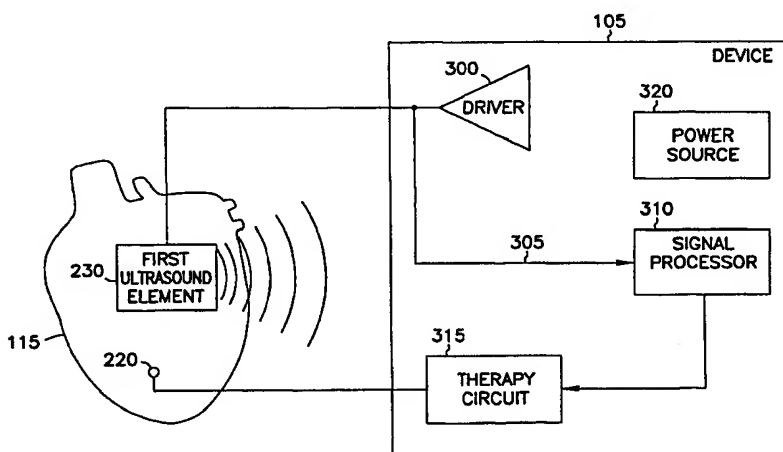




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<b>(21) International Application Number:</b> PCT/US00/10570 <b>(22) International Filing Date:</b> 19 April 2000 (19.04.00)  <b>(30) Priority Data:</b> 09/294,641      19 April 1999 (19.04.99)      US  <b>(71) Applicant:</b> CARDIAC PACEMAKERS, INC. [US/US]; 4100 Hamline Avenue North, St. Paul, MN 55112 (US). <b>(72) Inventor:</b> SWEENEY, Robert, J.; 7853 Cobblestone Road, Woodbury, MN 55125 (US). <b>(74) Agent:</b> VIKSNINS, Ann, S.; Schwegman, Lundberg, Woessner & Kluth, P.O. Box 2938, Minneapolis, MN 55402 (US).		<b>(81) Designated States:</b> AU, CA, JP, European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE).  <b>Published</b> <i>Without international search report and to be republished upon receipt of that report.</i>

(54) Title: ULTRASOUND FOR AUTOCAPTURE OR OTHER APPLICATIONS



## (57) Abstract

A cardiac rhythm management system provides ultrasound autocapture capability for determining whether a stimulation has evoked a desired response from the heart, and for adjusting an energy of the stimulation based on the observed response from the heart. A first ultrasound element is disposed on a lead in the heart. A second ultrasound element is disposed elsewhere in the heart or in the implanted device. An autocapture determination circuit determines whether motion of the heart chamber indicates a contraction in response to the stimulation, and adjusts the stimulation energy to provide only that energy which is needed to obtain capture. This saves energy, prolonging the life of the implanted device, minimizing the risk and expense to patient associated with early explantation and replacement of the implanted device. Other applications include using ultrasound for (1) determining the strength of heart contractions (2) determining dissociation between electrical and mechanical heart activity, (3) determining the volume of the heart, (4) determining the origin of sensed intrinsic electrical heart activity signals, (5) recognizing particular arrhythmias (6) disrupting cell membranes for lowering stimulation threshold, (7) controlling the delivery of a steroid, and (8) obtaining blood flow information.

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## ULTRASOUND FOR AUTOCAPTURE OR OTHER APPLICATIONS

### Technical Field

This invention relates generally to cardiac rhythm management systems and particularly, but not by way of limitation, to a cardiac rhythm management system with ultrasound autocapture capability for determining whether a  
5 stimulation has evoked a desired response from the heart.

### Background

When functioning properly, the human heart maintains its own intrinsic rhythm, and is capable of pumping adequate blood throughout the body's circulatory system. However, some people have irregular cardiac rhythms,  
10 referred to as cardiac arrhythmias. Such arrhythmias result in diminished blood circulation. One mode of treating cardiac arrhythmias uses drug therapy. Drugs are often effective at restoring normal heart rhythms. However, drug therapy is not always effective for treating arrhythmias of certain patients. For such patients, an alternative mode of treatment is needed. One such alternative mode  
15 of treatment includes the use of a cardiac rhythm management system. Such systems are often implanted in the patient and deliver therapy to the heart.

Cardiac rhythm management systems include, among other things, pacemakers, also referred to as pacers. Pacers deliver timed sequences of low energy electrical stimuli, called pace pulses, to the heart, such as via a  
20 transvenous leadwire or catheter (referred to as a "lead") having one or more electrodes disposed in or about the heart. Heart contractions are initiated in response to such pace pulses (this is referred to as "capturing" the heart). By properly timing the delivery of pace pulses, the heart can be induced to contract in proper rhythm, greatly improving its efficiency as a pump. Pacers are often  
25 used to treat patients with bradyarrhythmias, that is, hearts that beat too slowly, or irregularly.

Cardiac rhythm management systems also include cardioverters or defibrillators that are capable of delivering higher energy electrical stimuli to the heart. Defibrillators are often used to treat patients with tachyarrhythmias, that  
30 is, hearts that beat too quickly. Such too-fast heart rhythms also cause diminished blood circulation because the heart isn't allowed sufficient time to

fill with blood before contracting to expel the blood. Such pumping by the heart is inefficient. A defibrillator is capable of delivering an high energy electrical stimulus that is sometimes referred to as a defibrillation countershock. The countershock interrupts the tachyarrhythmia, allowing the heart to reestablish a normal rhythm for the efficient pumping of blood. In addition to pacers, cardiac rhythm management systems also include, among other things, pacer/defibrillators that combine the functions of pacers and defibrillators, drug delivery devices, and any other systems or devices for diagnosing or treating cardiac arrhythmias.

One problem faced by cardiac rhythm management systems is providing therapy at appropriate energy levels. In pacers, for example, pacing stimulations must have sufficient energy to capture the heart, that is, to initiate a resulting heart contraction. Delivering too much energy, however, will shorten the life of the battery powered implantable device. This, in turn, results in performing an earlier surgical explantation and replacement procedure, with its attendant risks and costs, both for the procedure and for the replacement device. Thus, there is a need to determine whether a cardiac rhythm management system is providing therapy at appropriate energy levels.

### **Summary**

This document describes, among other things, a cardiac rhythm management system with ultrasound autocapture capability for determining whether a stimulation has evoked a desired response from the heart, and for adjusting an energy of the stimulation based on the observed response from the heart. An autocapture determination circuit determines whether motion of the heart chamber indicates a contraction in response to the stimulation, and adjusts the stimulation energy to provide only that energy which is needed to ensure reliable capture. This saves energy, prolonging the life of the implanted device, minimizing the risk and expense to patient associated with early explantation and replacement of the implanted device.

In one embodiment, the cardiac rhythm management system includes a lead. The lead includes a distal end and a proximal end. The distal end of the lead is adapted for being disposed in or about a heart. The distal end of the lead includes a first ultrasonic element. An electronics unit is coupled to the proximal

end of the lead. The electronics unit includes an ultrasound driving circuit and a signal processing circuit that includes an autocapture determination circuit. In a first further embodiment, a second ultrasonic element is adapted for being disposed in a heart chamber different from the first ultrasonic element. In a  
5 second further embodiment, a second ultrasonic element is in a case carrying the electronics unit.

This document also discloses using the ultrasound for applications other than the ultrasound capability, including but not limited to: (1) determining the strength of heart contractions, such as from the slope of a signal transduced from  
10 the ultrasound, (2) determining dissociation between electrical and mechanical heart activity, (3) determining the volume of the heart, such as at different times during the cardiac cycle, (4) determining the origin of sensed intrinsic electrical heart activity signals based at least in part on information obtained from the ultrasound, (5) recognizing particular arrhythmias based at least in part on  
15 information obtained from the ultrasound, (6) delivering ultrasound for disrupting cell membranes for lowering stimulation thresholds, (7) using ultrasound to control the delivery of a steroid, and (8) obtaining blood flow information based at least in part on information obtained from the ultrasound. Other aspects of the invention will be apparent on reading the following detailed  
20 description of the invention and viewing the drawings that form a part thereof.

### **Brief Description of the Drawings**

In the drawings, like numerals describe substantially similar components throughout the several views. Like numerals having different letter suffixes represent different instances of substantially similar components.

25 Figure 1 is a schematic drawing illustrating generally one embodiment of portions of a cardiac rhythm management system and an environment in which it is used.

Figure 2 is a schematic drawing illustrating generally one embodiment of portions of a lead and an implanted device.

30 Figure 3 is a schematic drawing illustrating generally one embodiment of portions of a lead, an implanted device, and circuits included in the implanted device.

Figure 4 is a schematic drawing, illustrating generally one embodiment of transmission of ultrasound from the device to the ultrasonic element disposed in the heart.

Figure 5 is a schematic drawing, illustrating generally an embodiment including a first ultrasonic element in a first heart chamber and a second ultrasonic element disposed in another heart chamber.

Figure 6 is a schematic drawing illustrating generally an embodiment including a first ultrasonic element in a first heart chamber, a second ultrasonic element in another heart chamber, and a third ultrasonic element in the implanted device.

Figure 7 is a schematic drawing illustrating generally an embodiment including a single ultrasonic element in a first heart chamber for both providing and receiving ultrasound energy.

Figure 8 is a schematic drawing illustrating generally an embodiment providing capabilities other than autocapture.

#### **Detailed Description**

In the following detailed description, reference is made to the accompanying drawings which form a part hereof, and in which is shown by way of illustration specific embodiments in which the invention may be practiced. These embodiments are described in sufficient detail to enable those skilled in the art to practice the invention, and it is to be understood that the embodiments may be combined, or that other embodiments may be utilized and that structural, logical and electrical changes may be made without departing from the spirit and scope of the present invention. The following detailed description is, therefore, not to be taken in a limiting sense, and the scope of the present invention is defined by the appended claims and their equivalents. In the drawings, like numerals describe substantially similar components throughout the several views. Like numerals having different letter suffixes represent different instances of substantially similar components.

This document describes, among other things, a cardiac rhythm management system with ultrasound autocapture capability for determining whether a stimulation has evoked a desired response from the heart, and for

adjusting an energy of the stimulation based on the observed response from the heart.

Figure 1 is a schematic drawing illustrating generally, by way of example, but not by way of limitation, one embodiment of portions of a cardiac rhythm management system 100 and an environment in which it is used. In Figure 1, system 100 includes an implantable cardiac rhythm management device 105, which is coupled by an intravascular endocardial lead 110 to a heart 115 of patient 120. System 100 also includes an external programmer 125 providing wireless communication with device 105 using a telemetry device 130. Lead 110 includes a proximal end 135, which is coupled to device 105, and a distal end 140, which is coupled to one or more portions of heart 115.

Figure 2 is a schematic drawing illustrating generally, by way of example, but not by way of limitation, one embodiment of portions of lead 110 and device 105, with distal end 140 of lead 110 being disposed in right ventricle 200 of heart 115. Right atrium 205, left atrium 210, and left ventricle 215 are also illustrated. Distal end 140 of lead 110 includes at least one electrode, such as pacing tip electrode 220 and pacing ring electrode 225, for providing bipolar pacing stimulations to heart 115. Tip electrode 220 is coupled to device 105 by a first wire carried in lead 110. Ring electrode 225 is coupled to device 105 by a second wire carried in lead 110. Distal end 140 of lead 110 also includes a piezoelectric first ultrasonic element 230, located near ring electrode 225 and tip electrode 220, for transmitting ultrasound, receiving ultrasound, or both transmitting and receiving ultrasound. Device 105 includes a piezoelectric second ultrasonic element 235 for transmitting ultrasound, receiving ultrasound, or both transmitting and receiving ultrasound. In one embodiment, second ultrasonic element 235 is attached within a hermetically sealed case that encloses the electronic and other components of device 105. In another embodiment, second ultrasonic element 235 is included within a header portion extending from the hermetically sealed case, as illustrated in Figure 6.

Figure 3 is a schematic drawing illustrating generally, by way of example, but not by way of limitation, portions of heart 115, including first ultrasound element 230 and at least one electrode 220 disposed therein, and device 105, including second ultrasound element 235. In this embodiment, an

electrical driving signal at ultrasonic frequencies (e.g., 1-100 microsecond pulses of a 10 MHZ ultrasound signal) is provided by driver **300**, in device **105**, through conductors in lead **110** to first ultrasound element **230**. Transduced from this signal, first ultrasound element **230** emits ultrasound energy within heart **115**.

- 5 This ultrasound energy is received by second ultrasound element **235** in device **105**, which transduces it into an electrical signal that is provided, at node **305**, to signal processor **310**. Signal processor **310** includes amplification, demodulation, filter, analog-to-digital (A/D) conversion, digital-to-analog (D/A) conversion, memory, and other circuits for extracting and storing information  
10 obtained from the transduced ultrasound signal from second ultrasound element **235**. Portions of these circuits may be implemented as one or more sequences of instructions carried out on a microprocessor or other microcontroller.

- The signal at node **305** includes information about the movement of the heart chamber in which first ultrasound element **230** is disposed. Therapy circuit  
15 **315** delivers a pacing pulse stimulation via lead **110** to electrode **220** in right ventricle **200** (for example) of heart **115**. Such pacing stimuli are usually delivered at a time when the particular heart chamber is in a relaxed passive state and is being filled with blood. If the delivered pacing stimulus captures the heart, myocardial tissue near pacing site of electrode **220** begins to contract. If  
20 the delivered pacing stimulus does not capture the heart, such tissue does not begin to contract.

- In one embodiment, system **100** uses a measurement of the transit time of the ultrasound energy between first ultrasound element **230**, which is disposed in right ventricle **200**, and second ultrasound element **235**, in device **105** located at  
25 a reference point elsewhere in patient **120** outside heart **115**. The transit time of the ultrasound energy provides an indication of the physical distance between first ultrasound element **230** and second ultrasound element **235**. Variations in this distance represent movement of right ventricle **200**, in which first ultrasound element **230** is disposed, relative to device **105**. Such movement of right  
30 ventricle **200** results from contractions caused by the pacing stimulations or intrinsic electrical heart activity. The presence or absence of such movement during an appropriate time period following the pacing stimulation indicates a resulting capture and no capture, respectively.



By monitoring movement over that portion of the cardiac cycle following the pacing stimulation, system **100** determines whether the pacing stimulation captured the heart. In one embodiment, the movement observed (during an appropriate time window initiated by the pacing stimulation) is compared to a threshold value, which corresponds to the movement expected even in the absence of an evoked contraction. If the movement observed exceeds this threshold value, then system **100** indicates that capture was successfully obtained. If, upon expiration of the appropriate time period, system **100** determines that the heart was not captured, then system **100** issues a second pacing stimulation, of sufficiently large energy to obtain capture. In another embodiment, movement is monitored over a plurality of cardiac cycles to determine whether, over a period of time, the pacing stimulations capture the heart. For each pacing stimulation, if no capture is indicated upon expiration of the time window triggered by the pacing stimulation, then a second pacing stimulation of sufficient energy to obtain capture is delivered.

One autocapture method of determining the appropriate energy level starts with the delivery of a high energy pacing stimulation to the heart. The energy is reduced during subsequent pacing stimulations (e.g., by reducing pacing amplitude or pulse duration), until the movement observed indicates that capture was not obtained. System **100** then increases the energy back to a level known to be adequate to obtain capture. This autocapture determination can be made intermittently or, alternatively, may represent a particular mode that can be set to operate continuously.

In another embodiment, system **100** uses a Doppler shift measurement of movement of the right ventricle **200**. In this embodiment, the change in frequency of the ultrasound signals transmitted by the first ultrasound element **230** (and received by second ultrasound element **235**) is frequency demodulated to represent movement of right ventricle **200** as it contracts and expands. A higher frequency signal represents motion of the first ultrasound element **230**, in right ventricle **200**, toward device **105**. A lower frequency signal represents motion of the first ultrasound element **230**, in right ventricle **200**, away from device **105**. In a further embodiment, both transit time and Doppler shift measurements (or other like measurements) are used.

System **100** includes an autocapture determination module (e.g., a sequence of instructions carried out on the microcontroller in signal processor **310**) that determines whether motion of the heart chamber indicates a contraction in response to the delivered stimulation. The autocapture determination module  
5 adjusts the stimulation energy (either the amplitude of the pacing voltage pulse or the time period, i.e., pulsewidth, during which the pacing stimulation is being delivered) to provide only that stimulation energy which is needed to obtain capture. As a result, the energy delivered by therapy circuit **315** is optimized such that, over many such cardiac cycles, pacing stimulations are delivered at  
10 optimized reduced energies. This, in turn, prolongs the life of power source **320** (e.g., a battery) and the implanted device **105**, minimizing the risk and expense to patient **120** associated with early explantation and replacement of device **105**.

Figure **4** is a schematic drawing, similar to Figure **3**, illustrating generally, by way of example, but not by way of limitation, another embodiment  
15 of portions of system **100** in which driver **300** is coupled to second ultrasound element **235** for emitting ultrasound energy received by first ultrasound element **230** in heart **115**, where it is transduced into an electrical signal that is provided, at node **305**, to signal processor **310**. This embodiment also contemplates one or more of transit time, Doppler shift, or other like measurements of the motion of  
20 first ultrasound element **230** to detect whether a stimulation from therapy circuit **315** obtains a resulting contraction of heart **115**.

Figure **5** is a schematic drawing, including aspects that are similar to those described with respect to Figure **2**, illustrating generally, by way of example, but not by way of limitation, another embodiment of portions of  
25 system **100** in which device **105** is also coupled to a second heart chamber, i.e., right atrium **205**, through lead **110B**. Second lead **110B** also includes tip electrode **220B**, ring electrode **225B**, and second ultrasonic element **230B**. In this embodiment, a stimulation is delivered to right ventricle **200** and its movement is detected by providing ultrasound at first ultrasound element **230A**  
30 and receiving the ultrasound at second ultrasound element **230B** (or vice versa) to determine whether the stimulation obtained a resulting contraction of right ventricle **200**. Similarly, a stimulation is delivered to right atrium **205** and its movement is detected by providing ultrasound at second ultrasound element

**230B** and receiving the ultrasound at first ultrasound element **230A** (or vice versa) to determine whether the stimulation obtained a resulting contraction of right atrium **205**.

Figure 6 is a schematic drawing, similar to Figures 2 and 5, illustrating generally, by way of example, but not by way of limitation, another embodiment of portions of system **100** in which device **105** also includes a third ultrasonic element **235**. This embodiment also illustrates, by way of example, locating third ultrasonic element **235** in a header portion extending from the hermetically sealed case. Alternatively, third ultrasonic element **235** is located in the hermetically sealed case, as illustrated in Figure 2. In the embodiment of Figure 6, a stimulation is delivered to right ventricle **200**, and its movement is detected by providing ultrasound at first ultrasound element **230A** and receiving the ultrasound at third ultrasound element **235** (or vice versa) to determine whether the stimulation obtained a resulting contraction of right ventricle **200**. Similarly, a stimulation is delivered to right atrium **205**, and its movement is detected by providing ultrasound at second ultrasound element **230B** and receiving the ultrasound at third ultrasound element **235** (or vice versa) to determine whether the stimulation obtained a resulting contraction of right atrium **205**.

Figure 7 is a schematic drawing illustrating another embodiment of portions of system **100** in which a single ultrasound element, such as first ultrasound element **230**, both provides and receives ultrasound energy. In this embodiment, first ultrasound element **230** is coupled to driver **300**. Ultrasound element **230** converts electrical energy provided by driver **300** into an ultrasound energy pulse that is delivered to heart **115**. Then, driver **300** is turned off, and ultrasound element **230** receives reflected ultrasound energy, such as from any acoustic boundary, for example, the interior wall of heart **115**. The ultrasound energy reflected from the heart wall and received by ultrasound element **230** is transduced by ultrasound element **230** into an electrical signal that is provided, at node/bus **305** to signal processor **310**.

In one embodiment, variations in the transit time of the received ultrasound energy that is reflected from the heart wall provides an indication of the movement of the heart due to a contraction. In another embodiment, variations in the Doppler shift of the received ultrasound energy that is reflected

from the heart wall provides an indication of the movement of the heart due to a contraction. In a further embodiment, both transit time and Doppler shift measurements (or other like measurements) are used. Using the techniques described above, system **100** includes an ultrasound autocapture method that  
5 determines whether a particular pacing stimulation captured the heart based on the ultrasound indication of movement of the heart during a time window following the pacing stimulation.

#### Other Applications

Although it is described above primarily with respect to using ultrasound  
10 for providing autocapture capability, system **100** includes also other uses, as illustrated generally, by way of example, but not by way of limitation, in the schematic drawing of Figure 8. In a first example, the ultrasound signal provides information about mechanical heart contractions. The ultrasound signal is transduced and processed to obtain an electrical signal that includes information  
15 about the heart contractions. From the slope other characteristics of this electrical signal, a slope detection module **800** determines the strength of the heart contraction. In one embodiment, the slope detection module **800** is implemented as a sequence of instructions executed by signal processor **310**. For example, stronger contractions occur during a shorter period of time,  
20 corresponding to a larger slope in the ultrasonically transduced mechanical heart contraction signal. This information is used for diagnostic purposes (e.g., communicated to programmer **125**) or to adjust therapy, such as by adjusting rate, timing, or energy to maximize the strength of the heart contraction.

In a second example, the ultrasound signal provides information about  
25 mechanical heart contractions. Intrinsic electrical heart activity signals obtained, at sensing circuit **815**, from the lead electrodes. These intrinsic electrical heart activity signals are also referred to as electrogram signals. The electrogram signals provide information about the electrical heart activity which causes the heart contractions. The ultrasound and the electrogram signals are compared by  
30 a dissociation detection module **805** implemented as a sequence of instructions executed in signal processor **310** to determine whether, and to what degree, there exists any dissociation between the time of intrinsic electrical heart activity and the corresponding resulting mechanical contractions of the heart. This

information is used for diagnostic purposes (e.g., communicated to programmer 125) or to adjust therapy, such as by adjusting rate, timing, or energy delivered to optimize the relationship between intrinsic electrical heart activity and the mechanical contractions of the heart.

5           In a third example, the ultrasound signal provides information about mechanical heart contractions. The ultrasound signal is transduced and processed to obtain an electrical signal that includes information about the heart contractions. From the amplitude or other characteristics of this signal, the filling and end diastolic volume of the heart is determined. In one example, a  
10   amplitude detection module 810, such as a peak detection module implemented as a sequence of instructions executed in signal processor 310, is used to obtain an indirect measure of the volume of the heart using amplitude measurements. This information is used for diagnostic purposes (e.g., communicated to programmer 125). For example, increases in heart volume may indicate  
15   degeneration toward congestive heart failure (CHF). Alternatively, the ultrasonic signal information is used to adjust therapy, such as by adjusting rate, timing, or energy delivered to maximize cardiac output or efficiency.

          In a fourth example, the ultrasound signal provides information about mechanical heart contractions. Electrogram signals, from sensing circuit 815,  
20   provide information about the electrical heart activity that causes the heart contractions. Such electrogram signals may include far-field sensing of electrical heart activity associated with heart chambers other than the heart chamber in which the electrode providing the signal is located. The ultrasonically obtained heart contraction information is used to augment the  
25   electrical heart activity information from sensing circuit 815 for better determining the origin of the sensed electrical heart activity (e.g., near-field or far-field) so that therapy can be provided based on a more accurate determination of heart activity. Conversely, the ultrasound signal may include components associated with heart chambers other than the heart chamber associated with the  
30   ultrasound element. In such a case, the electrogram information may alternatively be used to better determine the origin of the ultrasonically-indicated mechanical heart contraction signal so that therapy can be provided based on a more accurate determination of heart activity.

In a fifth example, the ultrasound signal provides information about mechanical heart contractions. Electrogram signals from sensing circuit **815** provide information about the electrical heart activity that causes the heart contractions. Certain arrhythmias, such as sinus tachycardia and ventricular tachycardia are difficult to distinguish from each other based on electrogram signals. Moreover, defibrillation countershock therapy may be appropriate for a ventricular tachycardia, but unnecessary for a sinus tachycardia. However, the mechanical heart contraction signal characteristics are different for sinus tachycardia as compared to ventricular tachycardia. In one embodiment, system **100** discriminates between sinus tachycardia, ventricular tachycardia, and other arrhythmias based on the mechanical heart contraction signal obtained from one or more ultrasound elements disposed in one or more of right ventricle **200**, right atrium **205**, or other heart chamber. Anti-tachyarrhythmia therapy is tailored to the particular type of arrhythmia detected. In one embodiment, defibrillation countershocks are delivered for ventricular tachyarrhythmias, but are not delivered for sinus tachyarrhythmias. System **100** saves energy by avoiding the inappropriate delivery of defibrillation countershocks for sinus tachyarrhythmias. This minimizes the risk and expense to patient **120** associated with early explantation and replacement of device **105**. Avoiding inappropriate delivery of defibrillation countershocks also avoids irritating the heart and causing further arrhythmias. Even more importantly, system **100** decreases the risk of actually causing a ventricular tachyarrhythmia, such as life-threatening ventricular fibrillation, by inappropriately delivering a shock.

In a sixth example, the signal processor **310** controls operation of endocardial ultrasonic element **225** such that it delivers localized ultrasound energy pulses to at least partially disrupt cell membranes near the pacing tip electrode **220**. This is expected to lower the pacing threshold energy required to capture the heart **115** by decreasing the electrical resistance of cell membranes near the pacing electrode. One or more pacing pulses are then delivered at reduced energies, such as by using the autocapture techniques described above. This prolongs the usable life of implanted device **105**. In one embodiment, delivery of the ultrasound energy pulse is synchronized to delivery of a pacing pulse.

In a seventh example, the signal processor 310 controls operation of endocardial ultrasonic element 225 such that it modulates the release of a steroid from a nearby steroid eluting element, such as a polymeric steroid eluting matrix. In one example, a steroid eluting matrix is associated with nearby pacing  
5 electrode 220 to reduce the formation of scar tissue after implant so that lower pacing threshold energies are obtained. In one embodiment, device 105 delivers ultrasound energy to enhance the rate of steroid delivery. Because device 105 can accurately control the timing, duration, and energy of the ultrasound, increased control is obtained over the release of the steroid, which is ordinarily  
10 governed primarily by the physical characteristics of the steroid eluting matrix. In one embodiment, device 105 is programmably operated to release the steroid either more immediately after implant or after a desired time delay.

In an eighth example, the endocardial ultrasonic element 225 is used to measure blood flow in the heart chamber in which it is disposed, using transit  
15 time, Doppler shift, or other measurement techniques. This blood flow information is used for diagnostic purposes or to adjust therapy, such as by adjusting rate, timing, or energy delivered to maximize cardiac output based on the blood flow measurements.

#### Conclusion

20 The above-described system provides, among other things, a cardiac rhythm management system with ultrasound autocapture capability for determining whether a stimulation has evoked a desired response from the heart, and for adjusting an energy of the stimulation based on the observed response from the heart. An autocapture determination circuit determines whether motion  
25 of the heart chamber indicates a contraction in response to the stimulation, and adjusts the stimulation energy to provide only that energy which is needed to obtain capture. This saves energy, prolonging the life of the implanted device, minimizing the risk and expense to a patient associated with early explantation and replacement of the implanted device.

30 Although the system was described above primarily with respect to disposing an ultrasound element in the right ventricle for autocapture determination, it is understood that the system also includes application to ultrasonic autocapture determination in other heart chambers, and to the use of

ultrasound for applications other than autocapture, some of which are described above.

It is to be understood that the above description is intended to be illustrative, and not restrictive. Many other embodiments will be apparent to those of skill in the art upon reviewing the above description. The scope of the invention should, therefore, be determined with reference to the appended claims, along with the full scope of equivalents to which such claims are entitled.



WHAT IS CLAIMED IS:

1. A system, comprising:  
a lead, where the lead includes one or more ultrasonic elements; and  
an electronics unit coupled to the lead, where the electronics unit  
5 includes:  
an ultrasound driving circuit to drive at least one of the one or  
more ultrasonic elements; and  
a signal processing circuit that processes a signal based on  
ultrasound which is received by at least one of the one or more ultrasonic  
10 elements.
2. The system of claim 1, where the one or more ultrasonic elements  
include a first ultrasonic element, where ultrasound driving circuit drives the first  
ultrasonic element and where the first ultrasonic element receives the ultrasound.  
15
3. The system of claim 1, where the one or more ultrasonic elements  
include a first ultrasonic element and a second ultrasonic element, where the first  
ultrasonic element is coupled to the ultrasound driving circuit and the second  
ultrasonic element receives the ultrasound.  
20
4. The system of claim 1, where the one or more ultrasonic elements  
include a first ultrasonic element on the lead, and a second ultrasonic element in  
a case carrying the electronics unit.
- 25 5. The system of claim 1, in which the signal processing circuit includes an  
autocapture determination module.
6. The system of claim 1, in which the signal processing circuit includes a  
slope detection module.  
30
7. The system of claim 6, in which the slope detection module provides an  
indication of a strength of a mechanical contraction.

8. The system of claim 1, in which the signal processing circuit includes an amplitude detection module.
9. The system of claim 8, in which the amplitude detection module provides  
5 an indication of the volume of a contraction.
10. The system of claim 1, further including:  
an electrode; and  
a sensing circuit to detect intrinsic electrical activity based on at least one  
10 signal received from the electrode.
11. The system of claim 10, in which the signal processing circuit detects occurrences of activity based on both the ultrasound and the electrogram signal.
- 15 12. The system of claim 10, in which the signal processing circuit detects dissociation between an occurrence of activity based on the ultrasound and an occurrence of activity based on the signal.
13. The system of claim 10, in which the signal processing circuit recognizes  
20 an arrhythmia based at least in part on the ultrasound.
14. The system of claim 1, in which the signal processing circuit controls delivery of the ultrasound energy for lowering stimulation thresholds.
- 25 15. The system of claim 1, in which the signal processing circuit controls delivery of the ultrasound energy for controlling the release of a steroid from a steroid eluting element.
16. The system of claim 1, in which the signal processing circuit obtains  
30 blood flow information based on the ultrasound.
17. The system of claim 1, further including a programmer remote from the electronics unit.

18. A method, comprising:  
obtaining a first electrical signal, which includes mechanical contraction  
information, with a first ultrasonic element; and  
adjusting therapy based on the first electrical signal.
- 5
19. The method of claim 18, further including:  
transmitting ultrasound from the first ultrasonic element; and  
receiving ultrasound at a second ultrasonic element.
- 10
20. The method of claim 18, further including:  
transmitting ultrasound from a second ultrasonic element; and  
receiving ultrasound at the first ultrasonic element.
- 15
21. The method of claim 18, further including:  
transmitting ultrasound from the first ultrasonic element; and  
receiving ultrasound at the first ultrasonic element.
22. The method of claim 18, further including providing an autocapture  
function based on the first electrical signal.
- 20
23. The method of claim 18, further including detecting a volume of a  
mechanical contraction based on the first electrical signal.
24. The method of claim 18, further including detecting a second electrical  
25 signal including intrinsic electrical activity information.
25. The method of claim 24, further including detecting occurrences of  
activity based on both the first and second electrical signals.
- 30
26. The method of claim 24, further including detecting a dissociation  
between (1) an occurrence of activity based on the first electrical signal and (2)  
an occurrence of activity based on the second electrical signal.

27. The method of claim 24, further including recognizing an arrhythmia based at least in part on the first electrical signal.
28. The method of claim 18, further including controlling delivery of the  
5 ultrasound energy for disrupting cell membranes.
29. The method of claim 18, further including controlling delivery of the ultrasound energy for releasing a steroid.
- 10 30. The method of claim 18, further including obtaining blood flow information from the first electrical signal.
31. The method of claim 18, further including communicating information based on the ultrasound from an electronics unit to a remote programmer.

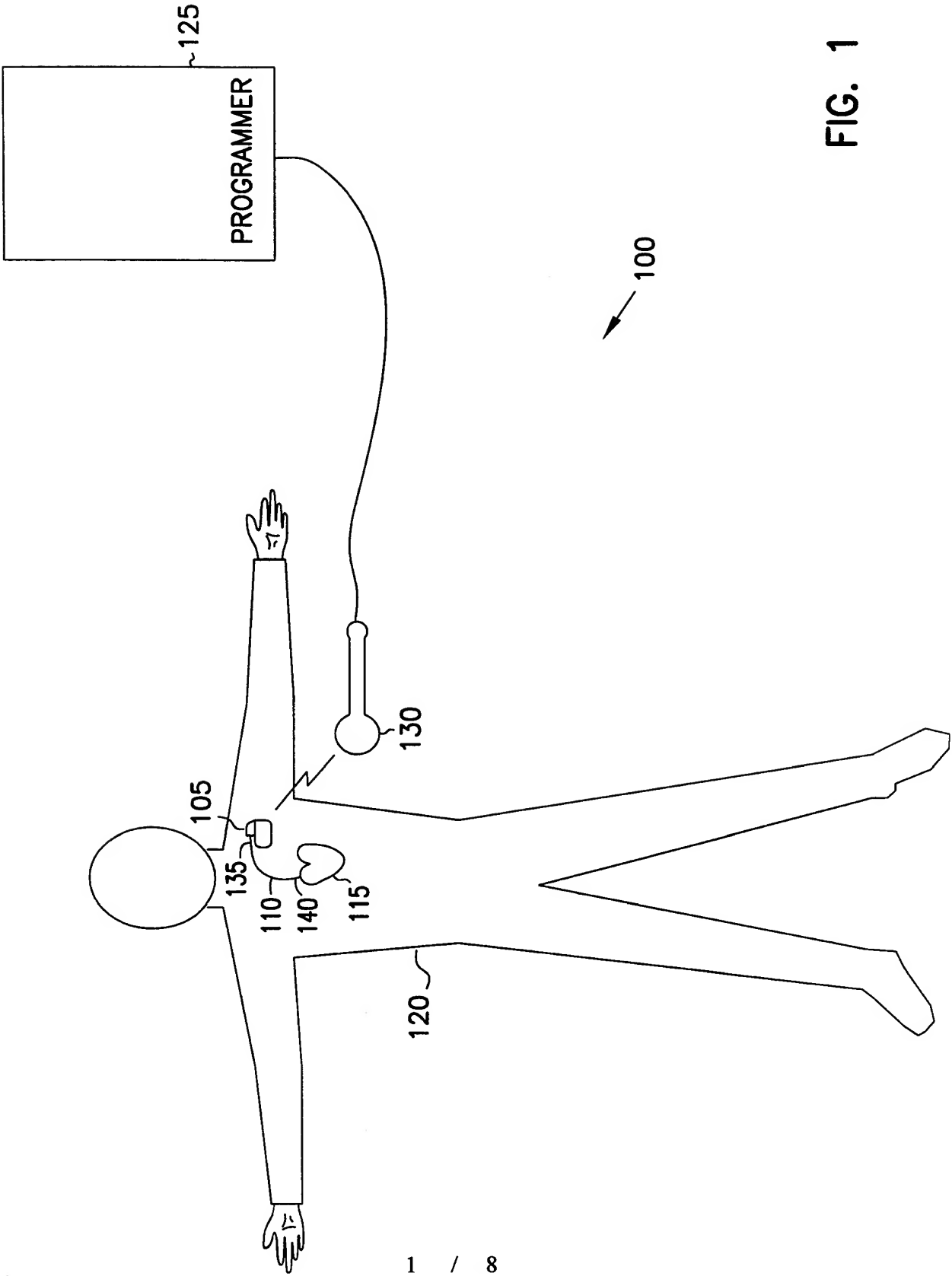
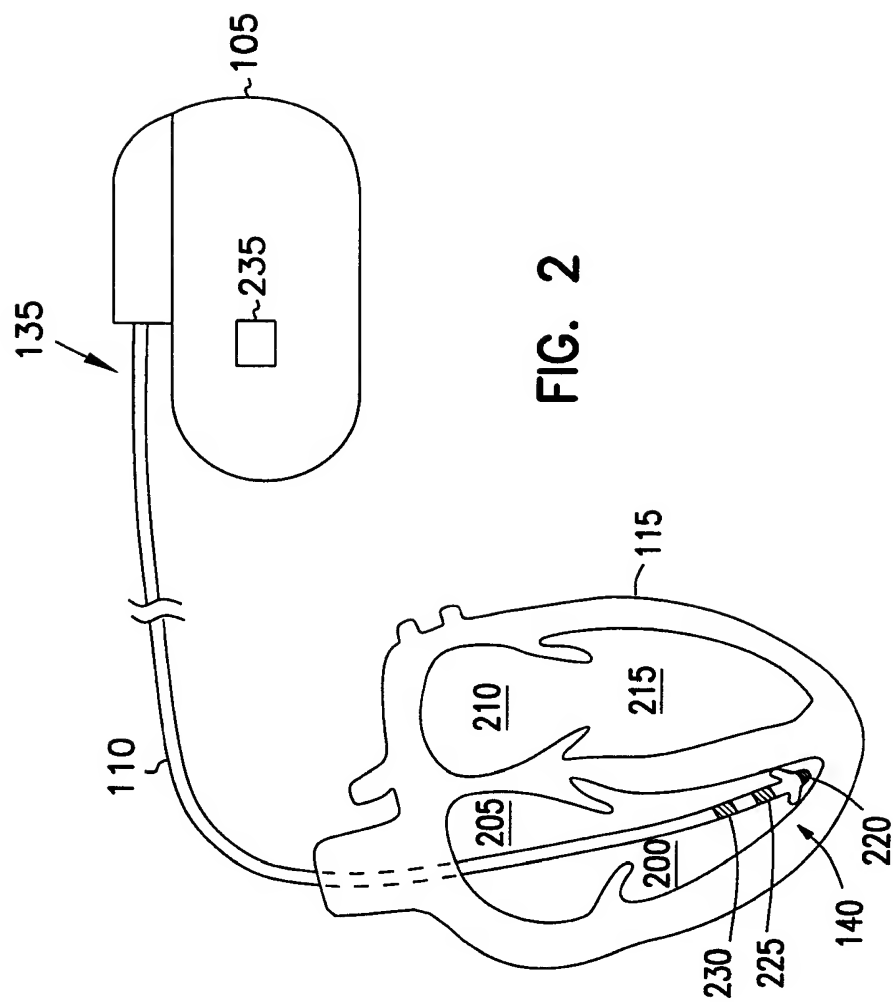


FIG. 1



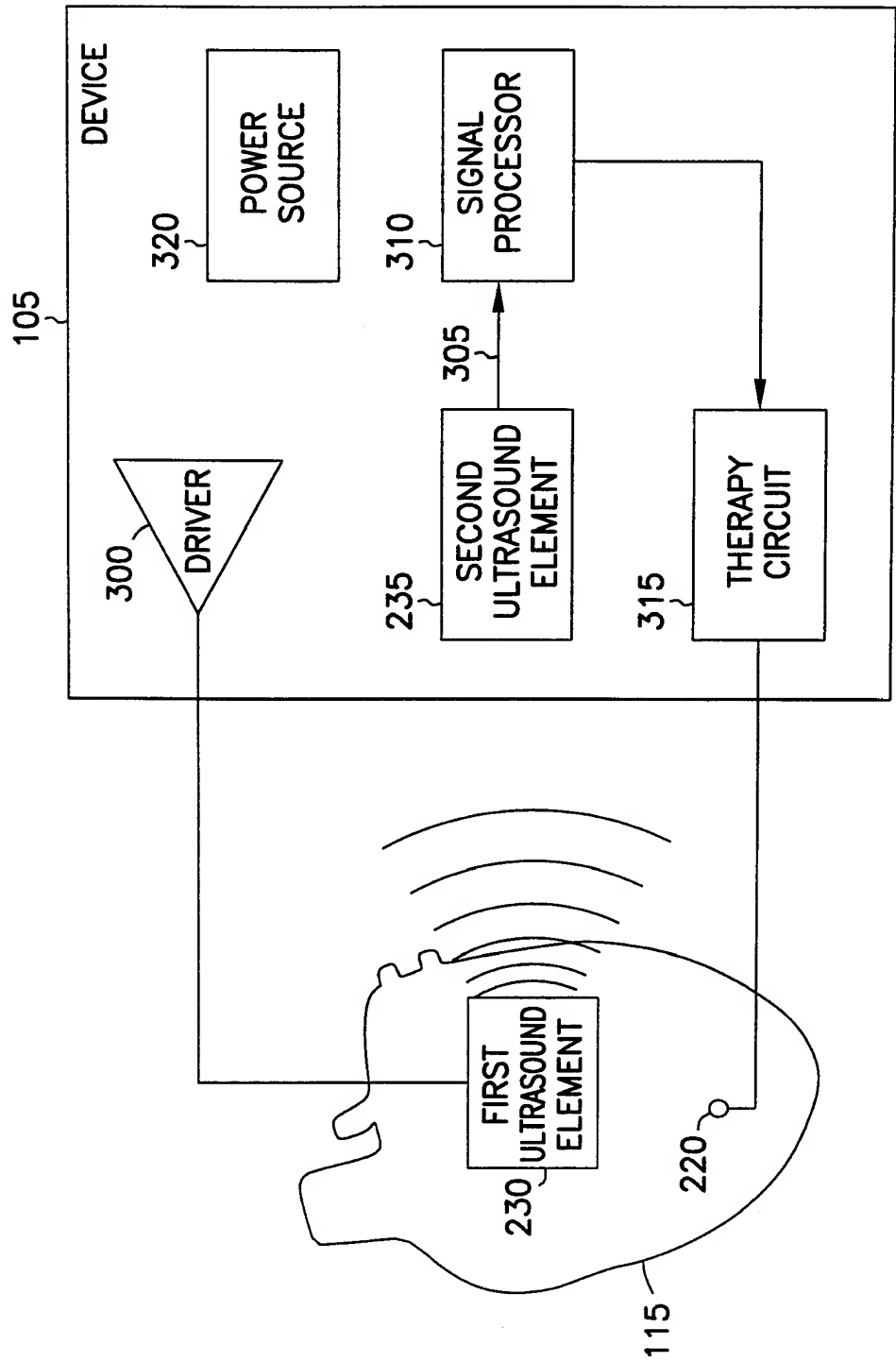


FIG. 3

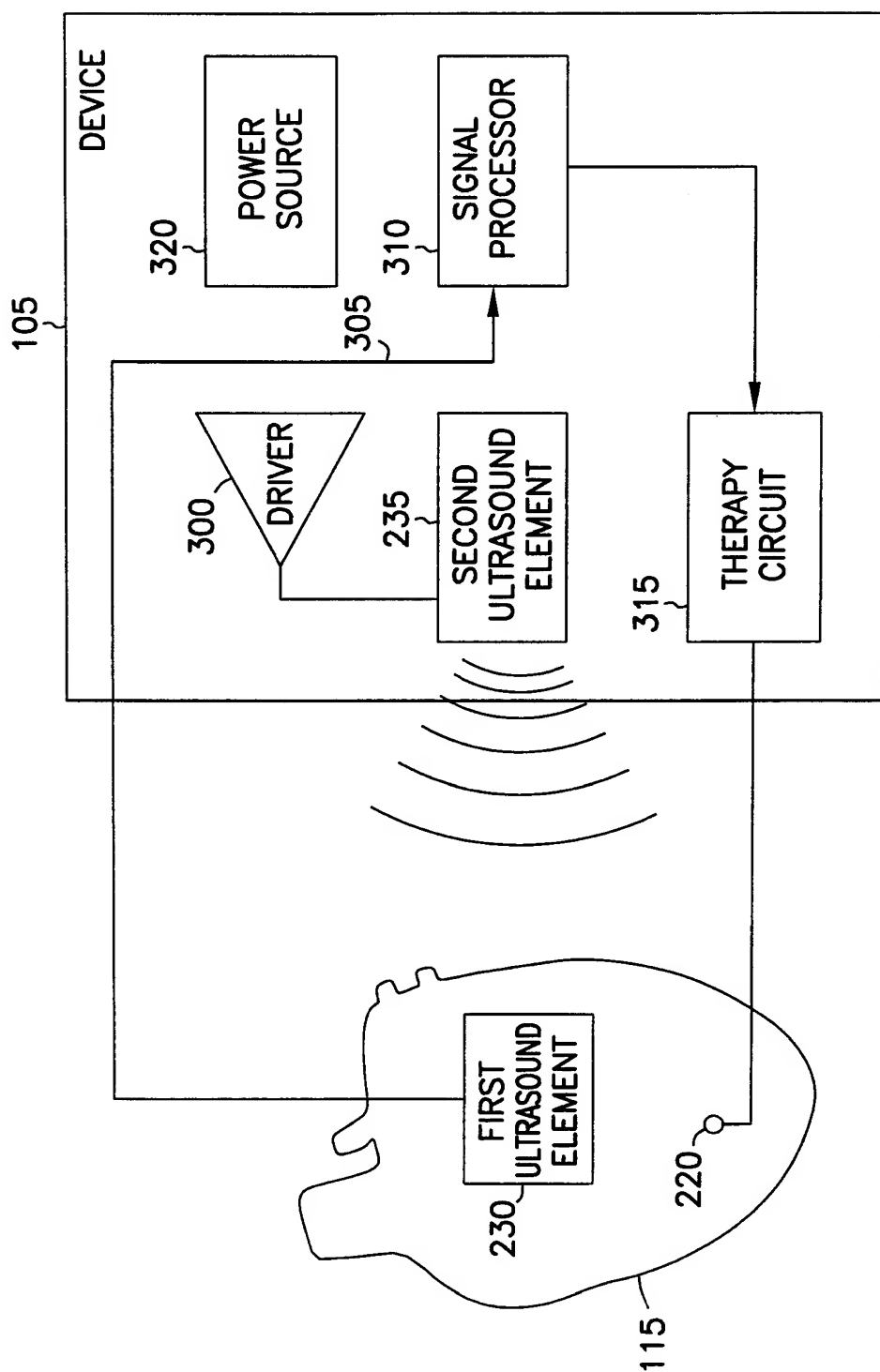


FIG. 4



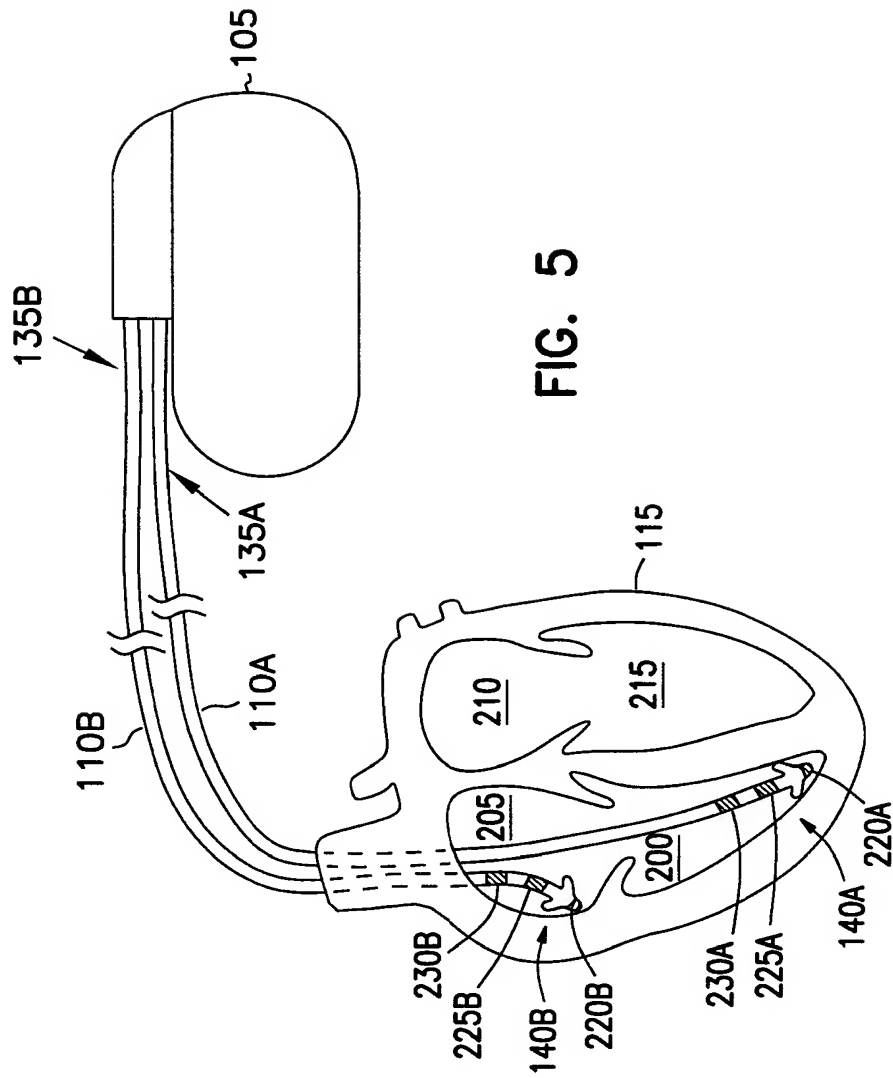
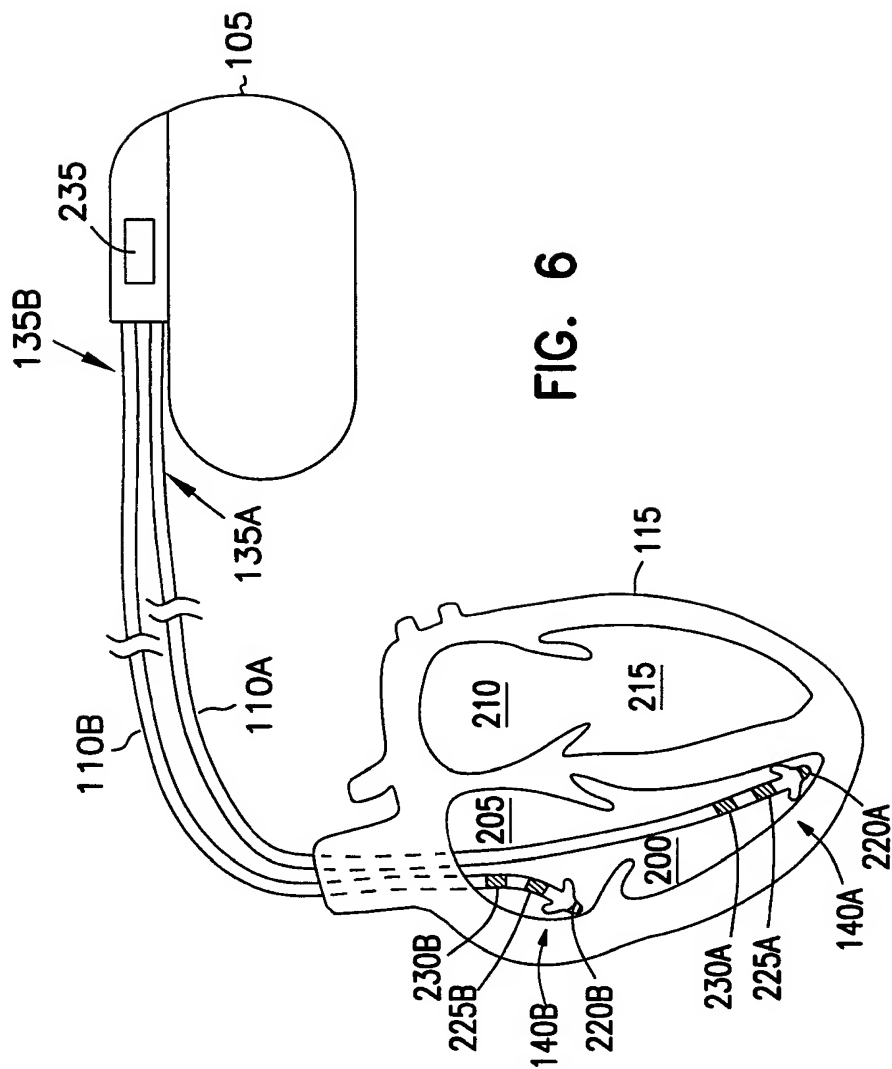


FIG. 5



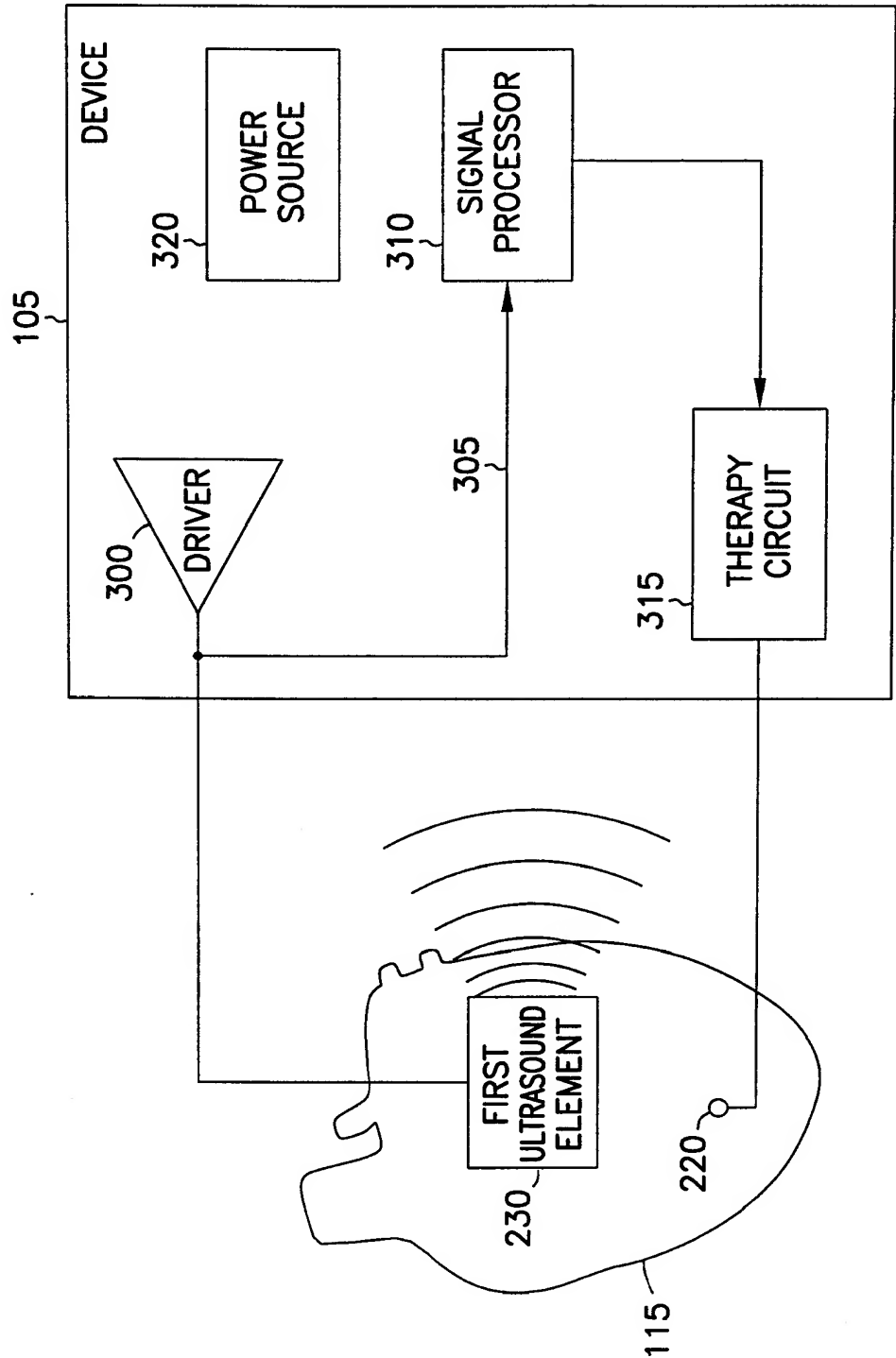


FIG. 7

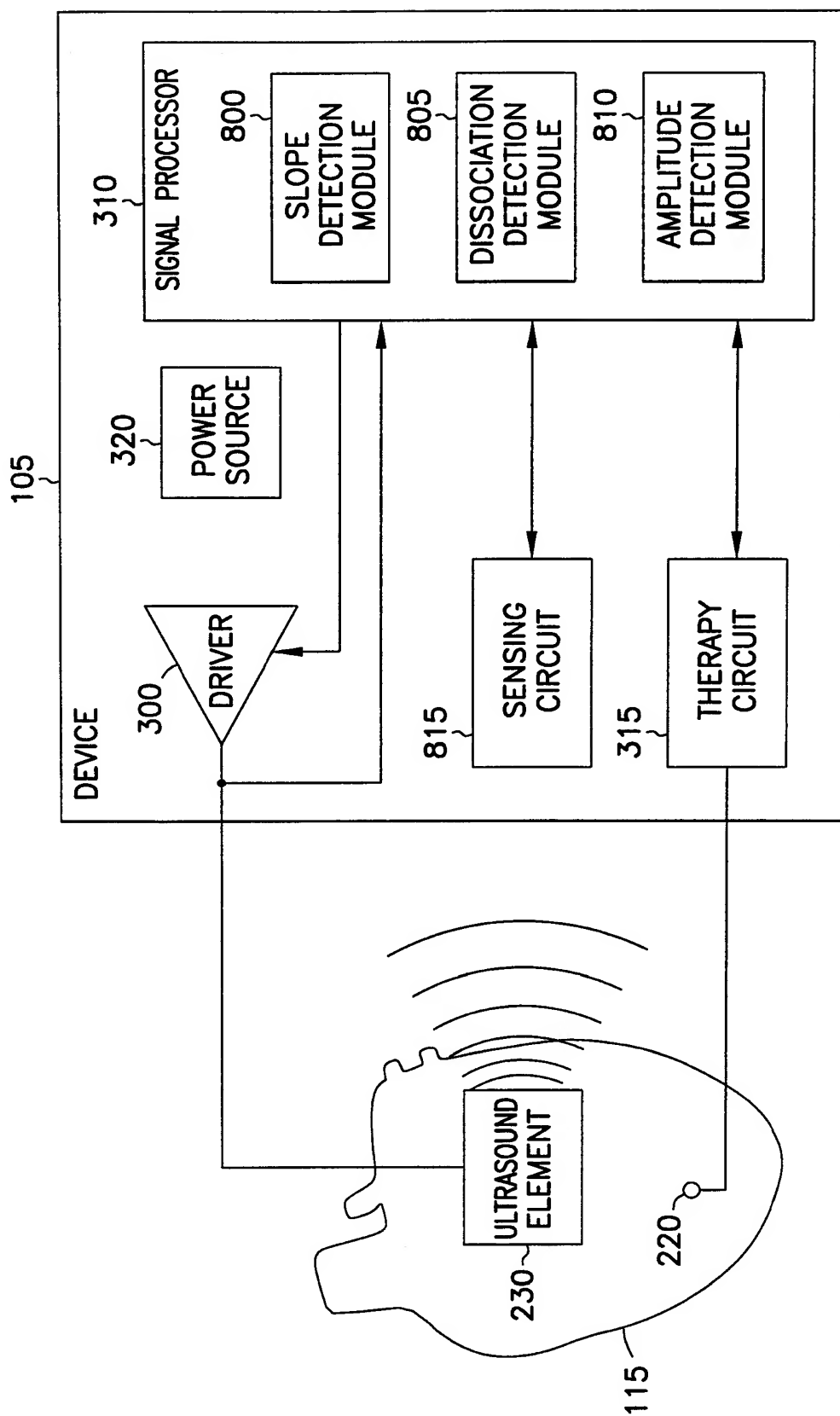


FIG. 8